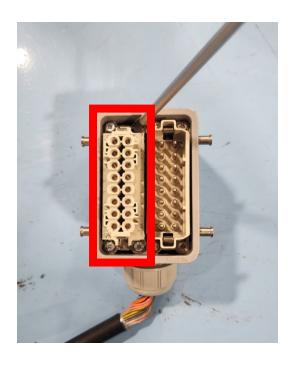
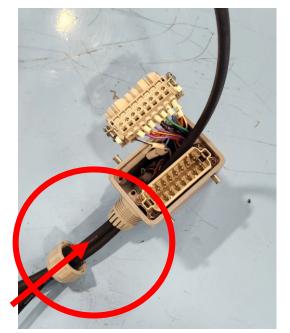
## Core Use / No Use Switch





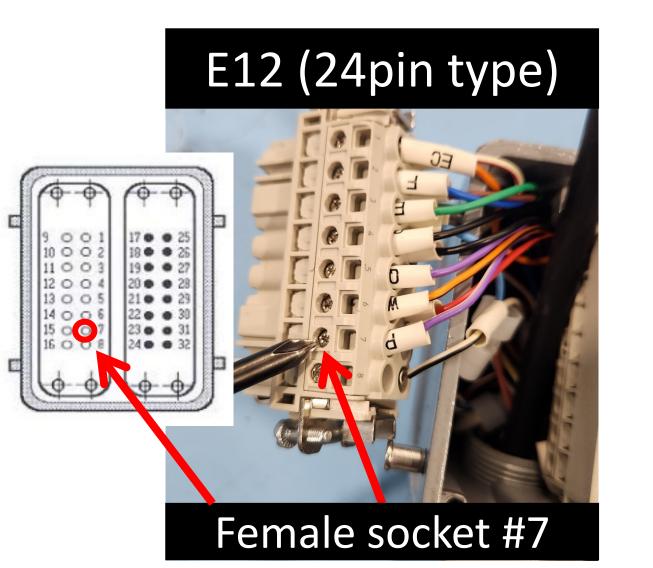
Open the right side (Female) of the Robot Plug.

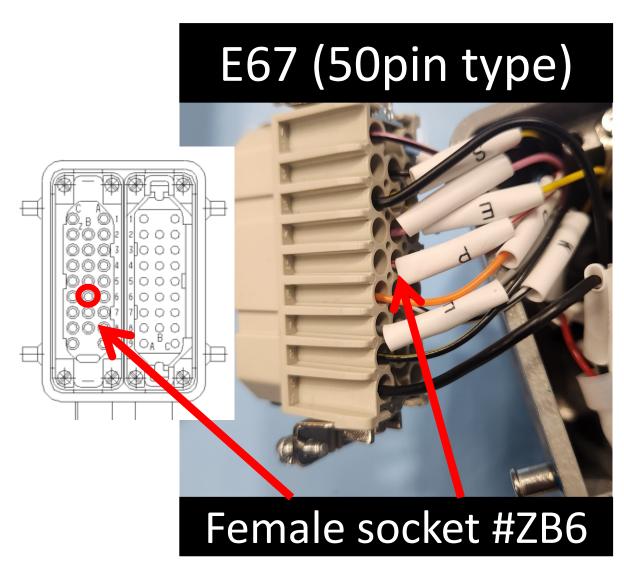


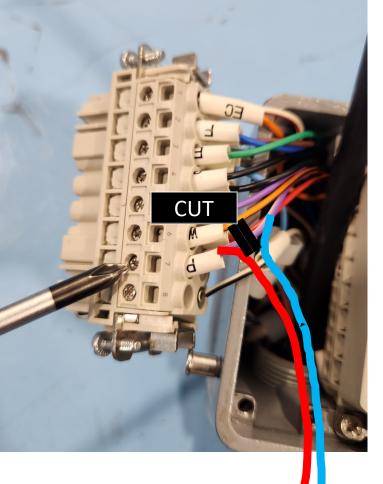
Insert the wire through the plug.

Check P wire.

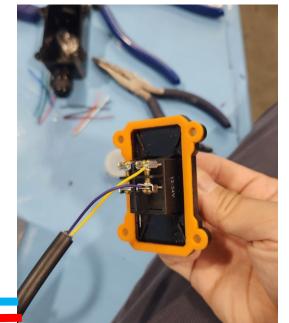
"P" is "CORE FWD (PULL)" signal from the machine.

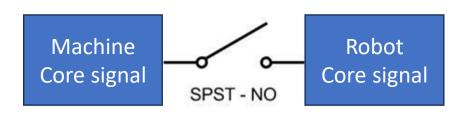






Cut the P wire.
Connect SPST switch
between the socket & plug wire





## **Core Use**



## Core No Use



Even if the core is used, if the robot does not need to control the core, the switch can be set to NO Use.