

# H5 QUICK REFERENCE

## 1. Power on the robot



Check whether the robot is at a safe place before moving on to the step 2.

If it is not at a safe place, then please move to a safe place by using Manual jog button.

## 2. Log In



- Level 7 - Professional allow to access entire systems and special settings
- Level 3 - Engineer allow to change the settings and edit the most of the programs
- Level 0 - Operator allow to access the basic settings and programs

## 3. Make A New Mold File & Load

Press



Press New

→ Type mold file name & Press Enter

→ Press Load

→ Check correct mold file is loaded

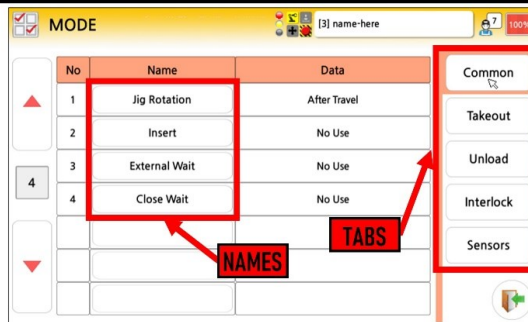


## 4. Mode Settings

Press



Press



Select Tabs → Press Name to change settings.

Example 1)  
Select Common → Press Jig Rotation → Set when to rotate EOAT

Example 2)  
Select Takeout → Press Takeout Method → Set what to use. Vac 1~4, Chuck or Gripper

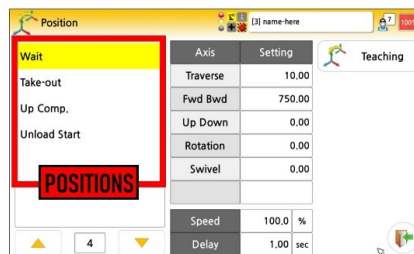
Example 3)  
Select Interlock → Press Type → Select Euromap 67 or Euromap 12

## 5. Position Settings

Press



Press



Default mold file has 4 positions.

- Wait
- Take-out
- Up Complete
- Unload Start

Select Positions you want to teach

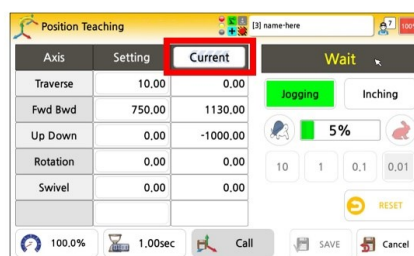
→ Press

Move the robot manually to the position.

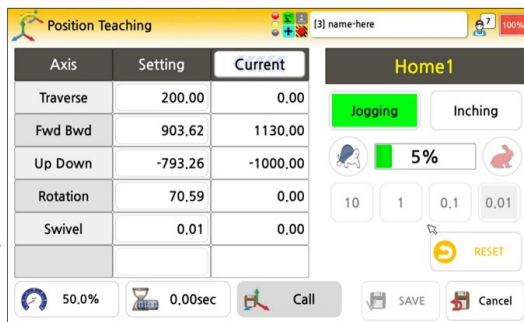
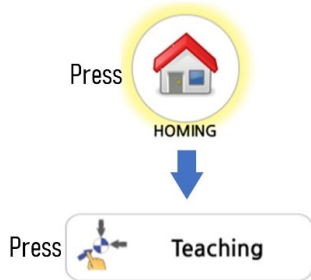
→ Press **Current** and

→ Press SAVE and

→ Repeat the same process for each positions



## 6. Home Setting



There are *two ways* of setting HOMING position

Move the robot manually to HOME position.

→ Press **Current** and 

→ Press  SAVE and  OK

**OR**

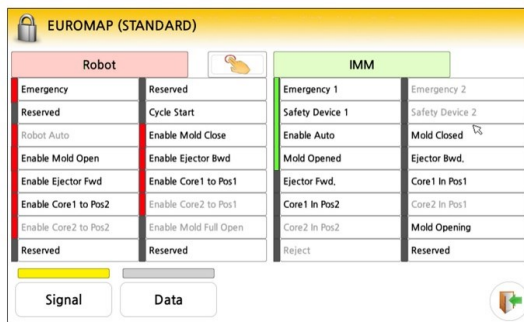
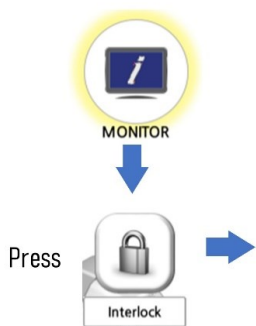
Set to the same position as WAIT position

Press  Call

→ Select WAIT and 

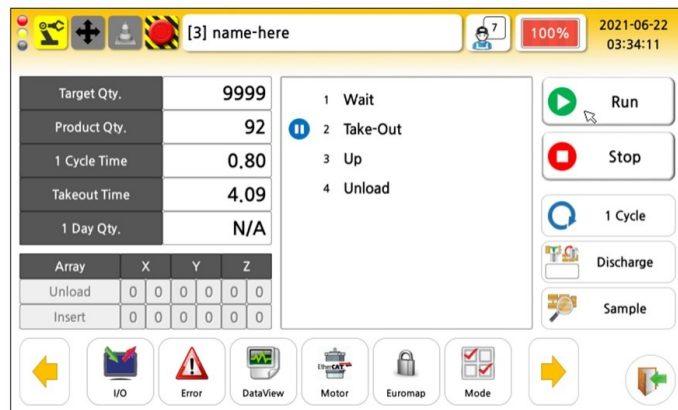
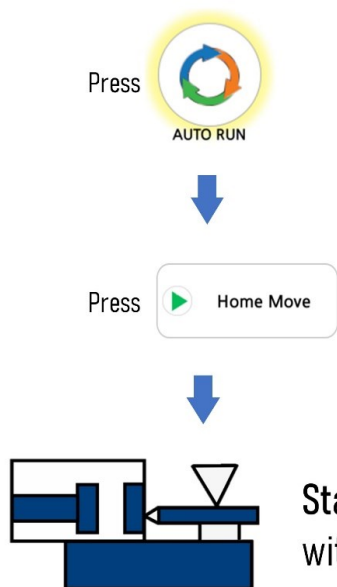
→ Press  SAVE and 

## 7. Check Interlock Signals



- Robot Emergency
- IMM Emergency
- Safety Device (if applicable)
- Mold Open / Close
- Enable Auto

## 8. Start Auto Run



During Injection cycle, press  Run