

EPIK / UNIK QUICK REFERENCE

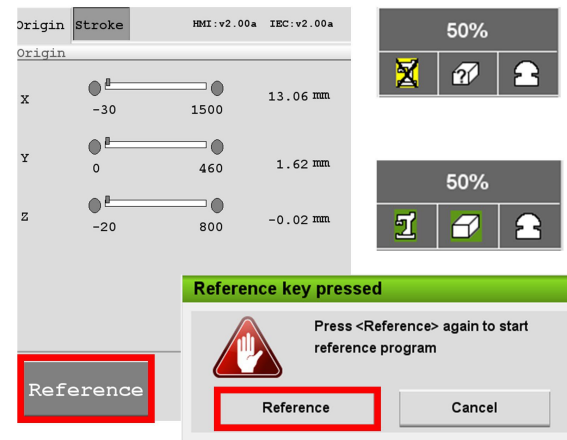
1. Power on the robot



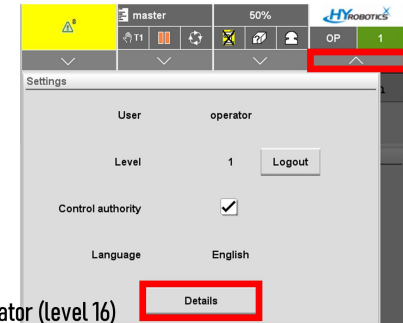
Check whether the robot is at a safe place before moving on to the step 2.

If it is not at a safe place, then please move to a safe place by using Manual jog button.

2. Reference

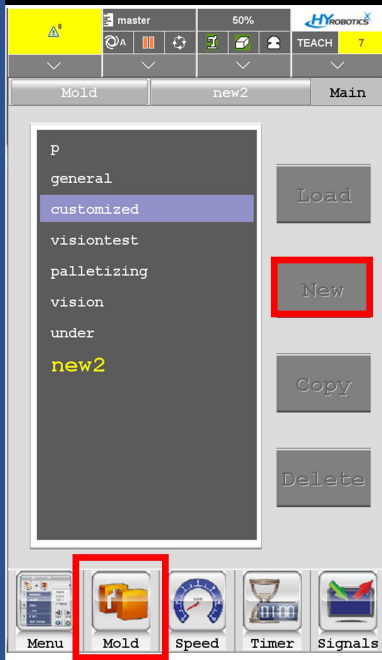


3. Log in



- Administrator (level 16) allow to access entire systems in controller
- Service (level 15) allow to change the settings and edit the basic programs
- Teacher (level 7) allow to access the basic settings and programs

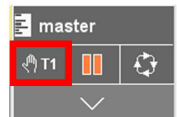
4. Make a New Mold File & Load



If the buttons are grayed out,



press manual op. button.



Check manual mode

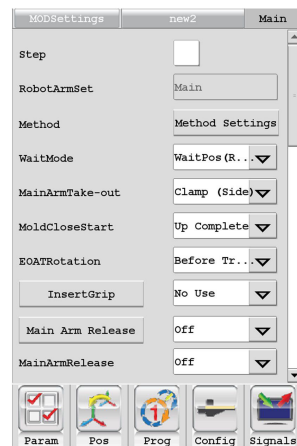
Mold file name must start with a letter, not number.

After new mold file is created, load it.

5. Basic Parameter Settings

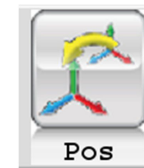


Press menu button



- Method: Vacuum & Gripper
- Clamp Side or Nozzle Side Take out?
- EOAT Rotation - when to rotate?
- Ejector Forward Control (If applicable)

6. Position Settings



Press position button



- Waiting Position
- Up Position
- Takeout Position
- Main Release Position

Move the robot with jog buttons, and **Teach**

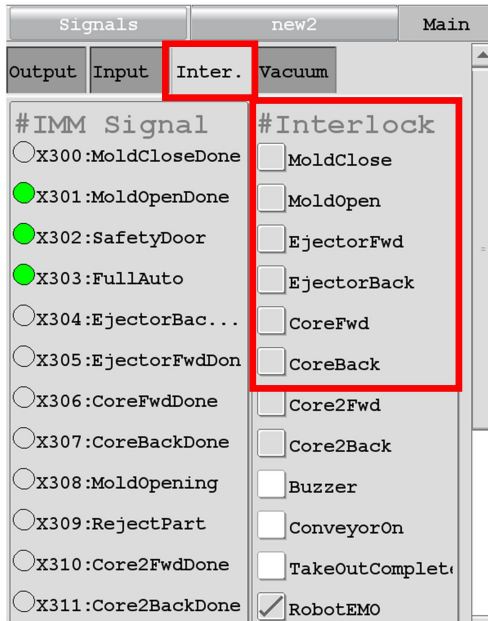
If the robot doesn't move, check if it is referenced & in manual mode.

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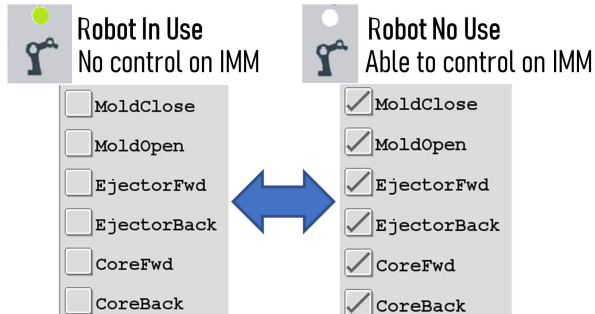
7. Check IMM / Interlock Signals



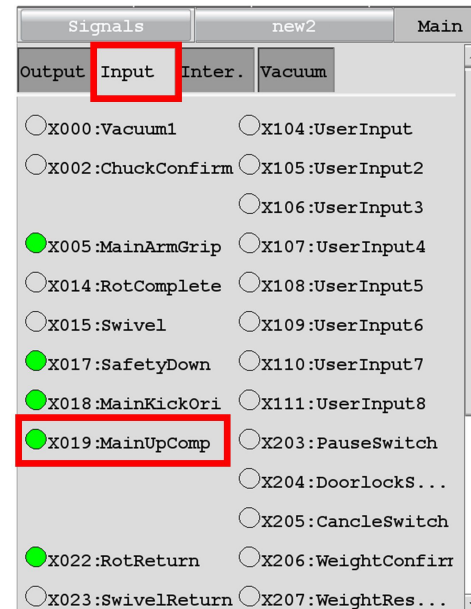
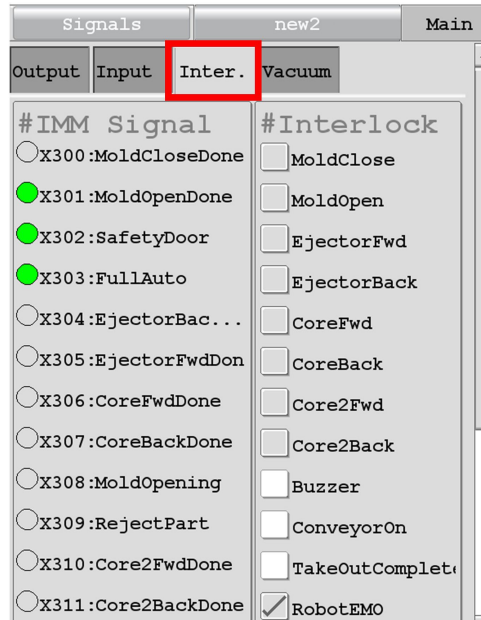
Press signal button
Go to Interlock tab



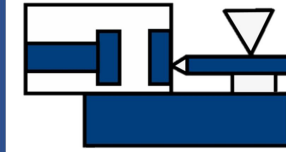
Press Robot In Use / No Use button,
check interlock signals.



8. Check other signals



9. Start Auto Run



Start IMM
with Auto run



During Injection cycle,
Press Homing button.



Press Auto Run button
Twice.



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