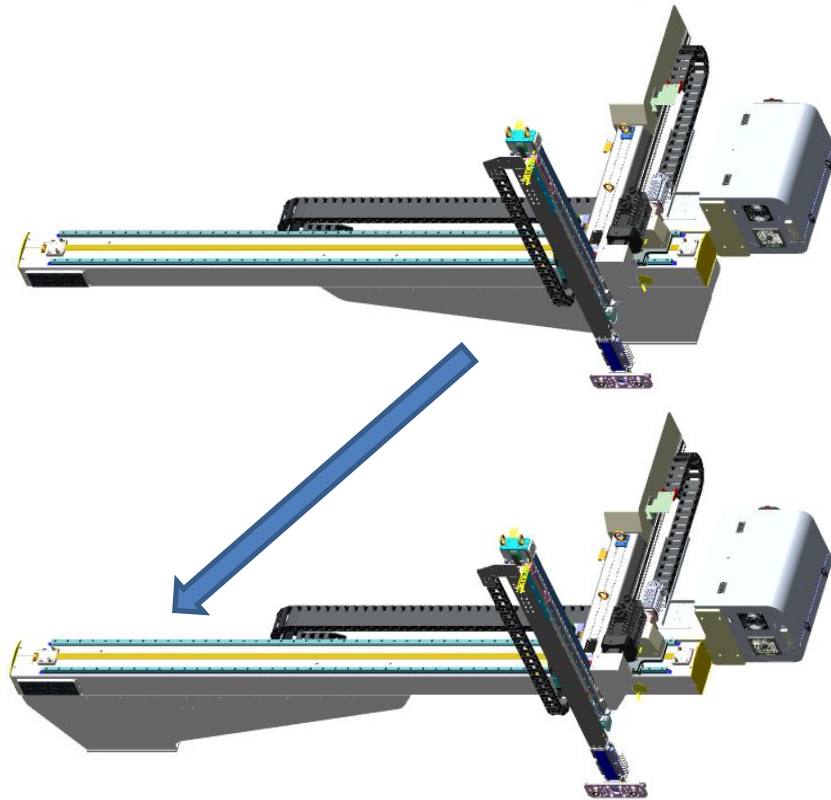
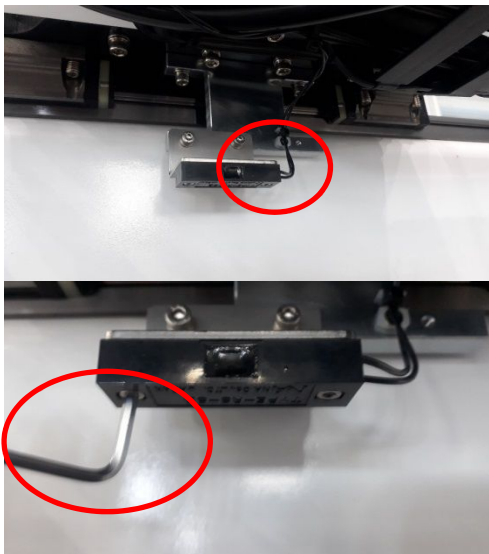


How to change Robot Direction from Non operator to Operator (EPIK, UNIK Robot)

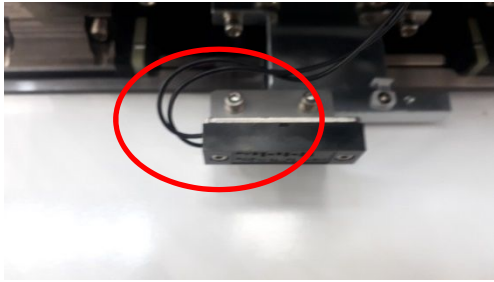
1. Disassemble body Frame from beam and rotate 180 Deg and assemble back (Control box can be move to other location if needed)



2. Change direction of sensor wire. (this will change in mold position)



Use 2.5mm Allen wrench and rotate sensor ,
so that wire can go to other side



3. Change servo motor drive direction (Pn001.0) (Traverse only)

From Control box, left side driver is traverse



Press M button to show Pn000



Press ▲ 1 times to change screen Pn001



Press ◀ button to go to date of Pn001 page



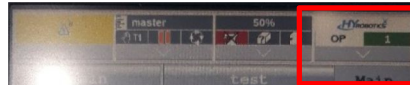
Press ▼ button to change 1 to 0
(CCW, CW 변경)



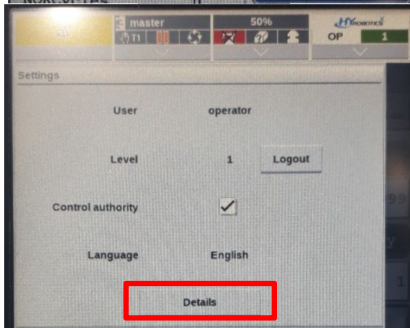
Press ◀ button to save and go out

Turn robot power off and turn on again.

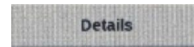
4. Change traverse origin offset point



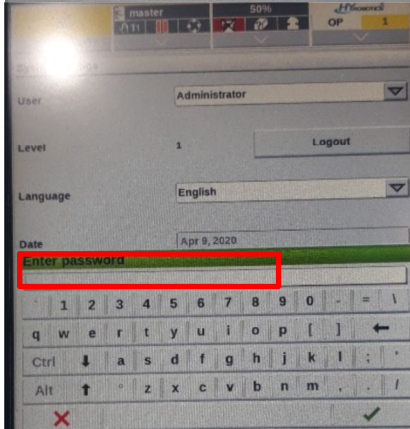
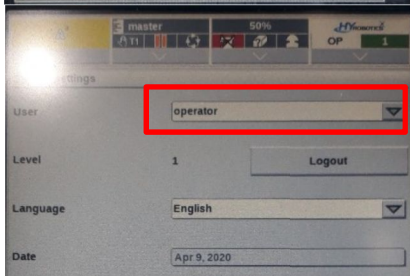
Touch Red box



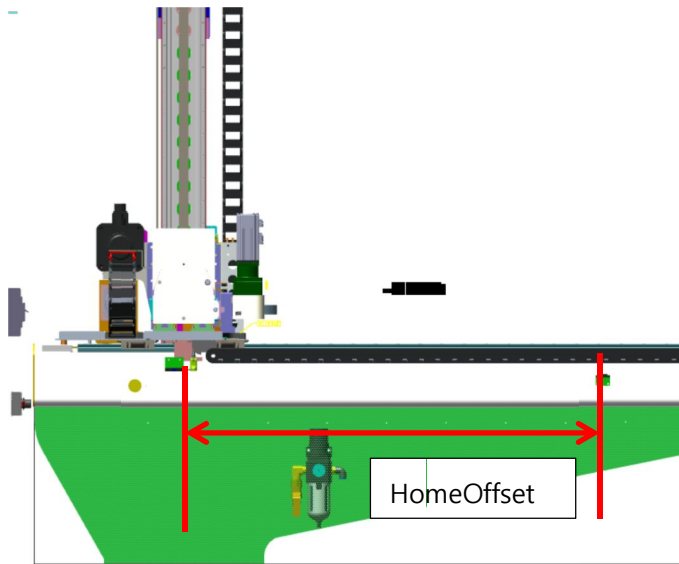
Touch



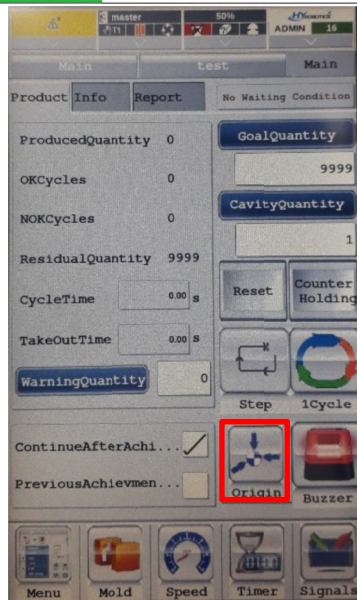
Select Administrator




Password input "pass"

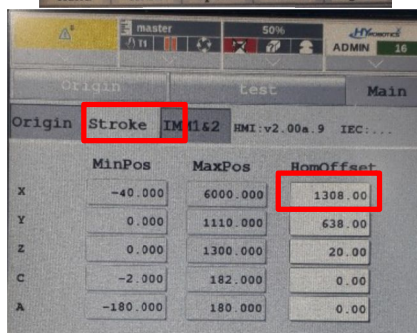


Measure distance from nozzle center to black color magnetic plate in the middle of back side of robot beam (HomeOffset) mm (for example : 1250 mm)



Press  to to move to Origin

Screen



Touch Stroke Tap input x HomOffset, input 1250 mm (Sample from above)

Turn off and turn on.