

## TP Simple Manual







- 1-1. User selection
  - User (0 Level) PW : 0000 <- Log in
- 1-2. Check if the currently selected mold is to be used (If the mold is to be using, move to STEP 3-3 for automatic operation)
- 1-3. Click on mold icon on Main screen

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- 2-1. Select the mold to use (When selected, the background screen turns yellow)
- 2-2. Click load in the right menu
- 2-3. Click OK in the load confirmation screen



Automatic

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3-1. Click OK in the load success screen

3-2. Click the close button below to go to the main screen

3-3. Click the auto- run on the main screen

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- 4-1. Click HomeMove to go to Home
- 4-2. Right button activated when completed
- 4-4. When driving button is clicked, change to pause button
  - Pause : Robot stops immed iately
  - Stop : Stop after one cycle

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- \*To exit the automatic page, press the pause or stop button to activate the close button while the robot is stopped
- 4-3. Click on the drive button to start automatic one cycle : When click the button, stop after one cycle
  - Defective product discharge : Move to the defective product discharge position and open if convergence (weight,temperature,etc.) measurement value is not normal(Caution : For defective product discharge, set the location of it where there is no mechanical interference)
  - Sampling : When it opens, go to the sampling location (Caution : For sampling, set the location of it where there is no mechanical interference)



- 1. Click Manual button on Main screen
- 2. Use the right keypad on the manual screen to manually operate the robot
- 1 CA 60 988.21 -393,5 -0.33 0,0 14 -1 a. (A)B **C** 
  - A : Turn I/O on and off manually
  - B : Current position value screen Selection jcg(HY/Joint/Trans)

C : Jog movement setting screen

Jogging: Movement while pressing the keypad Inching : Move to selected mm only once(10/1/0.1/0.01) Speed control: Turtle icon is deceleration, rabbit icon is acceleration

	6	Real	Set	Axis
Home Mo		0,11	0,06	Taxerse
$\sim$		988,28	988.08	Fwd8wd
		-393,51	-1380,41	UaDown
		-0,31	-0,32	Rotation
<ul> <li>Teaching</li> </ul>	-	0.02	0.02	Swivel

Caution



- 1. Click homing button on main screen
- 2. Movement to home position if homing motion button is pressed on homing screen

Set : home position Real : current position Location teaching : To go teaching page

When moving home, Inside of mold, crosswise ->vertical ->left/right&position(rotation method) \*Outside of mold, vertical - > crosswise&left/right&position(rotation method)

